

## **TRIPOD**

### **BACKGROUND OF THE INVENTION**

#### **1. Field of the Invention:**

The present invention relates to a tripod and, more  
5 particularly, to such a tripod, which can be controlled to  
automatically rotate the camera platform assembly with the carried  
video camera alternatively forwards and backwards within a  
predetermined range of angles.

#### **2. Description of the Related Art:**

10 A camera or photographing device may be supported on a  
tripod when taking photographs. A conventional tripod enables the  
loaded camera to be adjusted to the desired angle and elevation.  
However, conventional tripods do not have means to automatically  
alternatively rotate the loaded camera forwards and backwards  
15 within a predetermined range of angles, i.e. conventional tripods  
are not practical for use with a video camera for the purpose of  
monitoring a specific place.

### **BRIEF SUMMARY OF THE INVENTION**

The present invention has been accomplished under the  
20 circumstances in view. It is the main object of the present invention  
to provide a tripod, which can be controlled to automatically rotate  
the camera platform assembly with the carried video camera  
alternatively forwards and backwards within a predetermined range

of angles.

To achieve this and other objects of the present invention, the tripod comprises a supporting base for positioning, a rotary camera platform assembly fastened pivotally with the supporting  
5 base, a driving mechanism adapted to rotate the camera platform assembly alternatively forwards and backwards on the supporting base, and a control mechanism adapted to control rotation of the camera platform assembly within a predetermined range of angles. The control mechanism comprises a graduation dial disposed at a  
10 bottom side of the camera platform assembly above the supporting base for rotary motion with the camera platform assembly relative to the supporting base, a first micro switch adapted to control the driving mechanism to rotate the camera platform assembly forwards when triggered, a second micro switch adapted to control  
15 the driving mechanism to rotate the camera platform assembly backwards when triggered, a trigger rod mounted in the supporting base between the first micro switch and the second micro switch and adapted to trigger the second micro switch during forward rotation of the graduation dial with the camera platform assembly  
20 and the first micro switch during backward rotation of the graduation dial with the camera platform assembly, and a circuit module electrically connected to the first micro switch and the second micro switch and adapted to control the driving mechanism

to rotate the camera platform assembly on the supporting base forwards and backwards according to the triggering status of the first micro switch and the second micro switch.

## **BRIEF DESCRIPTION OF THE DRAWINGS**

5           FIG. 1 is a perspective view of a tripod according to the present invention.

FIG. 2 is an exploded view in an enlarged scale of a part of the tripod shown in FIG. 1.

10           FIG. 3 is an exploded view in an enlarged scale of the step motor and the graduation dial of the tripod shown in FIG. 1.

FIG. 4 is a schematic drawing showing the action of the camera platform assembly according to the present invention.

15           FIG. 5 is a schematic drawing showing the camera platform assembly switching from backward to forward rotation according to the present invention.

FIG. 6 is a schematic drawing showing the camera platform assembly switching from forward to backward rotation according to the present invention.

## **DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT**

20           Referring to FIGS. 1 and 2, a tripod in accordance with the present invention is shown comprising a supporting base 1, a camera platform assembly 2 fastened pivotally with the supporting base 1, a driving mechanism adapted to rotate the camera platform

assembly 2 alternatively in reversed directions, and a control mechanism adapted to control rotation of the camera platform assembly 2 on the supporting base 1 within a predetermined range of angles.

5           The supporting base 1 comprises a head 11, and three retractable legs 12 respectively and equiangularly hinged to the head 11 and adapted to support the tripod on the ground or a floor surface.

          The camera platform assembly 2 comprises a lower holder  
10 plate 21, an upper holder plate 22 hinged to the lower holder plate 21, and a camera platform 23. The upper holder plate 22 comprises a recessed top coupling hole 24, and a camera platform lock bar 25. The user can pull the camera platform lock bar 25 between two positions, namely, the locking position and the unlocking position.  
15 The camera platform lock bar 25 is moved to the unlocking position, and then the camera platform 23 is fitted into the recessed top coupling hole 24, and then the camera platform lock bar 25 is moved to the locking position to lock the camera platform 23 to the recessed top coupling hole 24 of the upper holder plate 22. Further,  
20 a lock 26 is provided between the upper holder plate 22 and the lower holder plate 21, and adapted to lock the upper holder plate 22 and the lower holder plate 21. When the lock 26 is unlocked, the camera platform 23 can be turned with the upper holder plate 22

relative to the lower holder plate 21 between the horizontal position and the vertical position. After adjustment of the camera platform 23 to the horizontal (or vertical) position, the upper holder plate 22 is locked to the lower holder plate 21 with the lock 5 26.

The aforesaid driving mechanism comprises a step motor 3 mounted in the head 11 of the supporting base 1.

The aforesaid control mechanism comprises a graduation dial 4 disposed at the bottom side of the camera platform assembly 10 2 above the head 11 of the supporting base 1 for rotary motion with the camera platform assembly 2, a trigger rod 5 mounted in the head 11 of the supporting base 1, a first micro switch 6 and a second micro switch 7 disposed at two sides of the trigger rod 5, and a circuit module 8 electrically connected to the first micro 15 switch 6 and the second micro switch 7 and adapted to control the operation of the step motor 3.

Referring to FIGS. 3 and 4 and FIGS. 1 and 2 again, the graduation dial 4 comprises 24 radial slots 40 equiangularly spaced around the periphery, a first stop rod 41, and a second stop rod 42. 20 The first stop rod 41 and the second stop rod 42 are selectively inserted into the radial slots 40, i.e., the user can determine the contained angle between the first stop rod 41 and the second stop rod 42. Further, the trigger rod 5 is disposed between the first stop

rod 41 and the second stop rod 42 in the path of the first stop rod 41 and the second stop rod 42 (see FIG. 4).

Referring to FIGS. 5 and 6, when starting the step motor 3 to rotate the graduation dial 4, the first stop rod 41 is moved with the graduation dial 4 to touch the trigger rod 5 (see FIG. 5). At this time, the trigger rod 5 is biased to trigger the first micro switch 6, thereby causing the circuit module 8 to give a control signal to the step motor 3 to reverse the direction of rotation of the step motor 3, and therefore the graduation dial 4 is reversed. During reverse rotation of the graduation dial 4, the second stop rod 42 will be moved to trigger the trigger rod 5 (see FIG. 6), thereby causing the trigger rod 5 to trigger the second micro switch 7. Upon triggering of the second micro switch 7, the circuit module 8 gives a control signal to the step motor 3 to reverse the direction of rotation of the step motor 3 again. Therefore, the graduation dial 4 is alternatively rotated forwards and backwards within the angles set by the first stop rod 41 and the second stop rod 42, i.e., the video camera or the like carried on the camera platform assembly 2 is alternatively rotated forwards and backwards with the camera platform assembly 2 and the graduation dial 4 to monitor a specific place within the set range of angles.

A prototype of tripod has been constructed with the features of FIGS. 1~6. The tripod functions smoothly to provide all of the

features discussed earlier.

Although a particular embodiment of the invention has been described in detail for purposes of illustration, various modifications and enhancements may be made without departing  
5 from the spirit and scope of the invention. Accordingly, the invention is not to be limited except as by the appended claims.